Middle School Mechatronics/Robotics Course Code: 21016

Rational Statement:

Robotics/Mechatronics exposes students to 21st century workplace skills and provides students with hands-on application of math and science concepts utilized in the real world.

Suggested Grade Level: 6-8

Topics Covered:

- Basic motor controls
- Solving Worldly Problems Using Robotics
- Basic Programming
- Mechanical systems
- Robotics and Entrepreneurship
- Career Possibilities

Core Technical Standards & Examples

Indicator 1: Understand the components that make up a robot		
Bloom's Taxonomy Level	Standard and Example	
Understanding	MSMR1.1. Know the equipment used in robotics	
	Example:	
	Identify types of sensors	
	 Explain various functions of motors 	
	Explain the role of a computer as a robotic control device	
Understanding	MSMR1.2. Identify various mechanical systems used in	
	robotics	
	Example:	
	Describe a belt and pulley speed reduction system	
	Recognize the importance and application of mechanical	
	advantages	
Applying	MSMR1.3. Demonstrate the use of programming commands	
	1 0 0	
	Example:	
	Compile a program to demonstrating a robotic "dance"	
	Develop a program to move the robot along a particular	
	shape	

Indicator 2: Investigate the impact of robotics on our society		
Bloom's Taxonomy Level	Standard and Example	
Analyzing	MSMR2.1. Compare and contrast robotics labor vs. human labor Example: Example: Explain the economic advantages/disadvantages of robotic labor Evaluate the decision of hiring 4 humans vs. 1 robot to do	
	the same job MSMB2.2. Explore sorror outlook for robotic applications	
Understanding	 MSMR2.2. Explore career outlook for robotic applications Example: Identify jobs that will be created/eliminated by robotics Brainstorm new robotics related careers 	
Understanding	 MSMR2.3. Explore new entrepreneurial opportunities using robotics Example: Discuss a fictitious business venture utilizing robotic labor Identify a business that could be improved using a robotic system 	
Indicator 3: Design a	robot to solve a particular problem	
Bloom's Taxonomy Level	Standard and Example	
Applying	 MSMR3.1. Identify robotic applications Example: In group discussion: consider the application of robotics Draw a robot and discusses the various differences in drawings 	
Applying	 MSMR3.2. Propose a robotic design Example: Sketch a diagram of a robotic "disk jockey" Present an idea to the class of how a robot can make your quality of life better 	
Applying	MSMR3.3. Construct a robot Example: Build a Lego robot	

	Use an Erector set to construct a robot
Applying	MSMR3.4. Program a robot
	Example:
	Write and download a program to make a robot navigate
	through a maze
	Write a program to make a robot follow a black line
	MSMR3.5. Evaluate robot programming
Applying	Example:
	 Record data on the preciseness of a program
	Analyze inconsistencies in the completion of a particular
	repetitive task